

## Brushless servo motors as replacements for conventional disk armature motors

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**motor**  
technology  
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## General information:

The Brushless servo motors series MCxx-BL from Mattke are permanent magnet synchronous motors designed in a very short mounting form. Thanks to the special construction of the motor flange they replace the formerly common disk armature motors from

### **PARVEX / AXEM / SERVALCO / ABB / BBC**

without any further mechanical modifications.

A very high power density is achieved by utilization of high quality materials. Excellent dynamic performances with high maximum speed also characterise these motors. The standard version is equipped with resolver; the motors are also available with incremental or absolute encoder upon request.

The main characteristics are:

- Rare earth magnets for high temperatures
- 8-pole construction
- Sinusoidal commutation
- Integrated thermal protection with PTC
- Rotatable angled connectors
- Compact design
- High protection, smooth surface
- High performance
- Flange and shaft dimensions compatible with disk armature motors

The values in this catalog are valid for the following conditions:

- Max. ambient temperature 40° C
- Min. ambient temperature 0° C
- Installation altitude up to 1000 m above mean sea level without restriction
- Isolation class F
- Effective values (RMS)
- Protection class IP65 (shaft excluded)

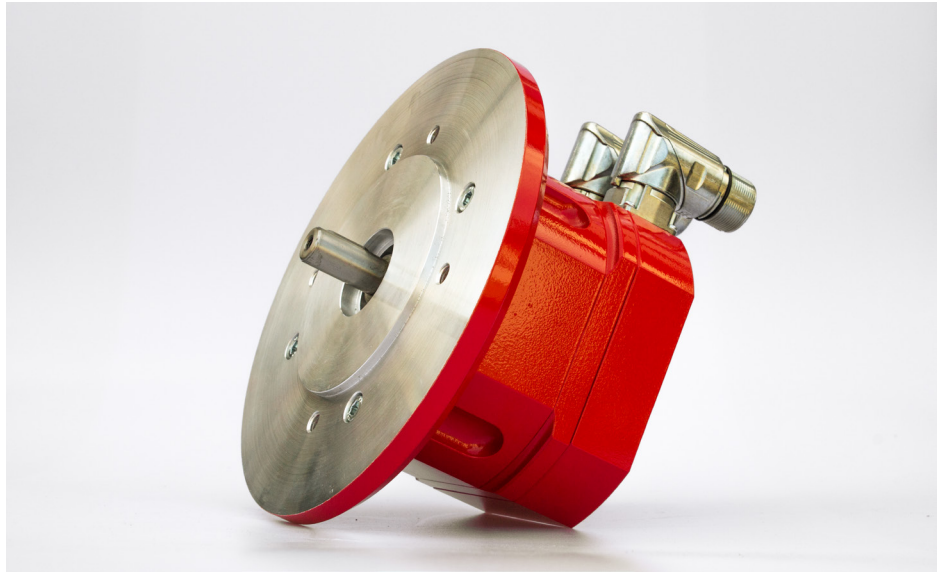
Comparison:



The following table shows the conventional disk armature motors and the equivalent brushless replacement:

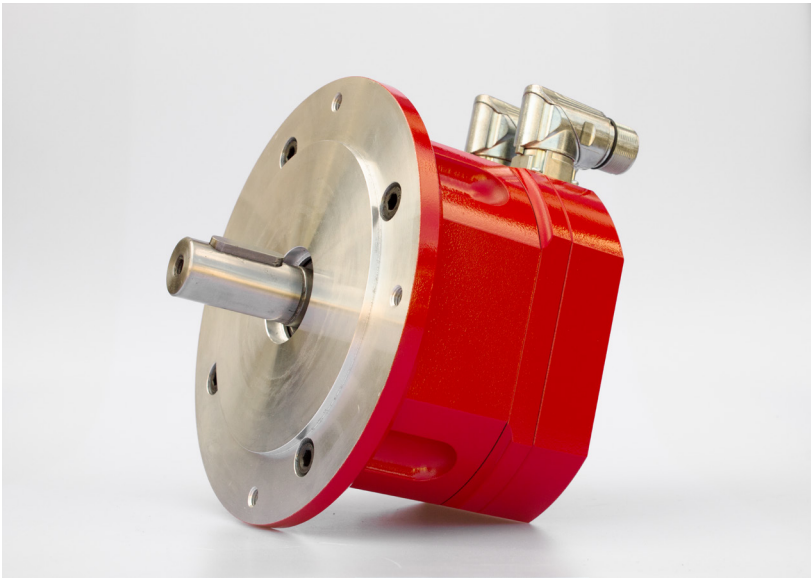
Disk armature motors	Disk armature replacement
MC 17 H, MC 17 B	MC 17-BL
MC 19 P, MC 19 S, MC 19 B	MC 19-BL
MC 23 S	MC 23-BL

## MC 17-BL



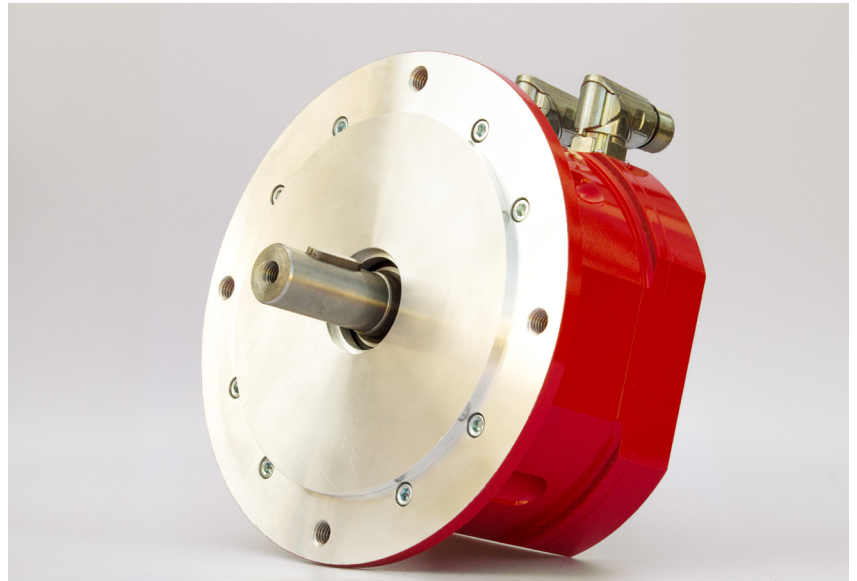
Description	Symbol	Unit	MC 17-BL
Stall torque	$M_0$	Nm	2.1
Max. voltage	$U_{\max}$	V	330
Stall current	$I_0$	A	2.1
Nominal current	$I_N$	A	1.8
Nominal torque	$M_N$	Nm	1.8
Nominal power	$P_N$	W	570
Nominal speed	$N_N$	$\text{min}^{-1}$	3000
Max. speed	$N_{\max}$	$\text{min}^{-1}$	5000
Peak current	$I_{\max}$	A	8
Voltage constant	$K_E$	V/Krpm	61
Torque constant	$K_T$	Nm/A	1
Rotor inertia	$J_R$	$\text{kg cm}^2$	2.8
Winding resistance at 20°C	$R_{U-V}$	Ohm	8.6
Winding inductance at 1 kHz	$L_{U-V}$	mH	16
Weight	m	kg	4.2

MC 19-BL



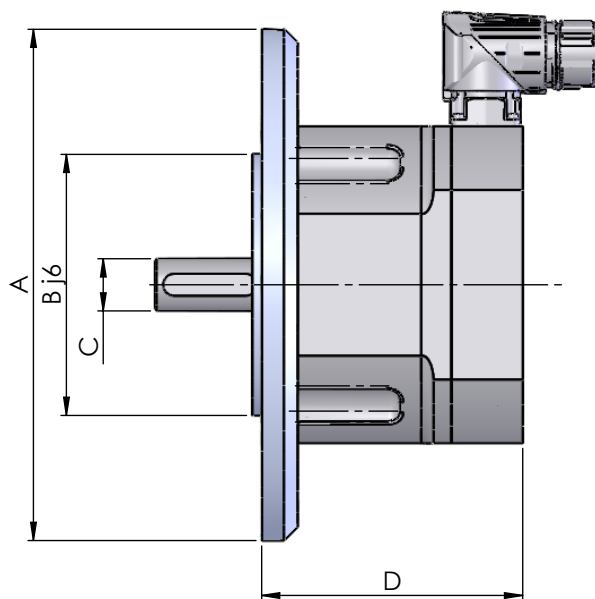
Description	Symbol	Unit	MC 19-BL
Stall torque	$M_0$	Nm	5
Max. voltage	$U_{max}$	V	350
Stall current	$I_0$	A	4.6
Nominal current	$I_N$	A	3.4
Nominal torque	$M_N$	Nm	3.6
Nominal power	$P_N$	W	1100
Nominal speed	$N_N$	min <sup>-1</sup>	3000
Max. speed	$N_{max}$	min <sup>-1</sup>	5000
Peak current	$I_{max}$	A	14
Voltage constant	$K_E$	V/Krpm	66
Torque constant	$K_T$	Nm/A	1.1
Rotor inertia	$J_R$	kg cm <sup>2</sup>	12
Winding resistance at 20°C	$R_{U-V}$	Ohm	2.3
Winding inductance at 1 kHz	$L_{U-V}$	mH	6.8
Weight	m	kg	6.4

## MC 23-BL

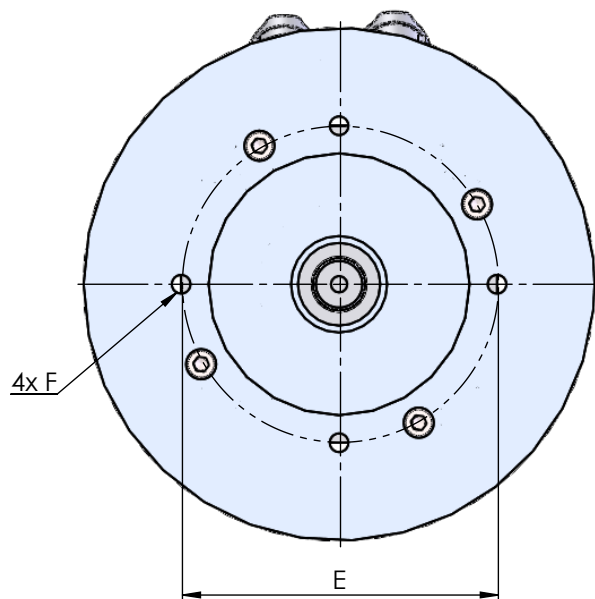


Description	Symbol	Unit	MC 23-BL
Stall torque	$M_0$	Nm	8
Max. voltage	$U_{\max}$	V	350
Stall current	$I_0$	A	6
Nominal current	$I_N$	A	5
Nominal torque	$M_N$	Nm	6.5
Nominal power	$P_N$	W	2000
Nominal speed	$N_N$	min <sup>-1</sup>	3000
Max. speed	$N_{\max}$	min <sup>-1</sup>	4000
Peak current	$I_{\max}$	A	18
Voltage constant	$K_E$	V/Krpm	80
Torque constant	$K_T$	Nm/A	1.32
Rotor inertia	$J_R$	kg cm <sup>2</sup>	27
Winding resistance at 20°C	$R_{U-V}$	Ohm	2.3
Winding inductance at 1 kHz	$L_{U-V}$	mH	10
Weight	m	kg	11

# Dimensions



Dimensions in mm



8

	MC 17-BL	MC 19-BL	MC 23-BL
A	ø186	ø186	ø242
Bj6	ø95	ø130	ø180
C	ø14	ø24	ø28
D	95	106.5	118
E	115	165	215
F	M8	M8	M12



Questions? Call us:

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